

Properties of eigenvectors

- ← The eigenvectors of a matrix form a linearly independent set
- If A ($M \times M$) has full rank, then the eigen vectors form the basis vectors for \mathbb{R}^M .
- If A is less than full rank with rank $q < M$, the first q eigenvectors span the subspace of A , the remaining span the nullspace of A .
- If A ($M \times M$) is real, symmetric, the eigenvectors not only form a linearly independent set, but they are orthogonal
→ Important!!

Proof: Let C be a real, symmetric matrix.
(Hartmann) For the eigenvectors e_k and e_j :

$$C e_j = \lambda_j e_j$$

$$C e_k = \lambda_k e_k$$

Transpose top equation and multiply by e_k .

$$e_j^T C^T e_k = \lambda_j e_j^T e_k$$

Multiply bottom equation by e_j^T

$$e_j^T C e_k = \lambda_k e_j^T e_k$$

Subtract the two equations:

$$e_j^T C^T e_k - e_j^T C e_k = (\lambda_j - \lambda_k) e_j^T e_k$$

If $C = C^T$ (symmetric matrix)

$$0 = (\lambda_j - \lambda_k) e_j^T e_k$$

Therefore unless the eigen~~values~~^{values} are equal (i.e. $\lambda_j = \lambda_k$), then

$$e_j^T e_k = 0$$

Therefore the eigenvectors must be orthogonal if the eigenvalues are distinct.

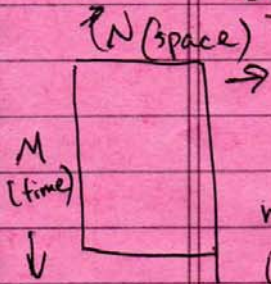
Introduction to EOF's

EOFs = Empirical Ortogonal Functions

Basic premise: Say have a data matrix with

M observations of length j ;

N state vectors ($M = \text{time}, N = \text{space}$)



We want to find the $1 \times N$ state vector (or the spatial pattern) that explains the largest fraction of the total variance of the data matrix.

Let e_1 (the 1st EOF) denote the vector (or spatial pattern) that has the highest possible resemblance to the whole ensemble of data $M \times N$. (and so on for EOF 2, 3, etc.)

Notes

- "Resemblance" is given by the mean projection of e_1 onto the ensemble of data.
- The projection is squared. (similar to squaring the error in linear regression)
- The vector e_1 is normalized such that its magnitude = 1. So only the direction of e_1 will impact the projection.
- ~~EOF~~ Dominant EOFs are sometimes (loosely) referred to as the dominant (spatial) modes.

Find e_1 that has the highest possible resemblance to the ensemble of state vectors

Want to maximize:

$$\lambda = \frac{1}{N} \left[\begin{array}{c} M \\ \text{(time)} \end{array} \begin{array}{c} N \text{ (space)} \\ \end{array} \begin{array}{c} e_1 \\ N \end{array} \right]^2$$

In matrix notation

$$\lambda = \frac{1}{N} (Ae_1)^T Ae_1 = \frac{1}{N} e_1^T \underbrace{A^T A}_C e_1$$

$C = \text{Covariance matrix}$

Recall

$$\begin{array}{c} A^T \\ N \\ M \end{array} \cdot \begin{array}{c} A \\ M \\ N \end{array} = \begin{array}{c} C \\ N \\ N \end{array}$$

$$\lambda = e_1^T C e_1$$

The eigenvectors have the following orthogonality property:

$$e^T e = I$$

Therefore can express this as an eigenvalue problem in the form:

$$C e_1 = \lambda e_1 \quad \text{or} \quad (C - \lambda I) e_1 = 0$$

What does this tell us about e_1 and λ ?

- 1) e_1 must be an eigenvector of the covariance matrix ($C = A^T A$) with the corresponding eigenvalue λ .
- 2) e_1 is the eigenvector that corresponds to the largest λ .
- 3) The eigenvectors of the covariance matrix C are called empirical orthogonal functions (EOFs).
- 4) The pattern that explains the largest fraction of the variance in a dataset A ($M \times N$) is the eigenvector corresponding to the largest eigenvalue of the covariance matrix ($A^T A$).

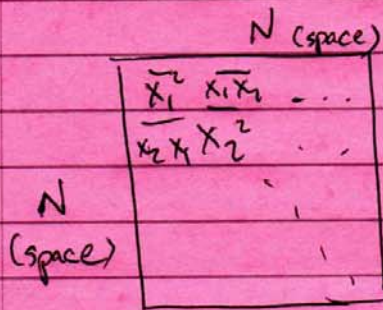
The subsequent EOFs (2nd, 3rd, etc.) are those corresponding to the second, third, etc. largest λ of $C = A^T A$.

$$C E = E L$$

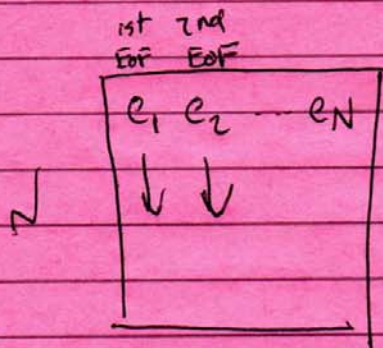
C = symmetric square matrix (cov. matrix)

E = matrix with columns corresponding to eigen vectors of covariance matrix.

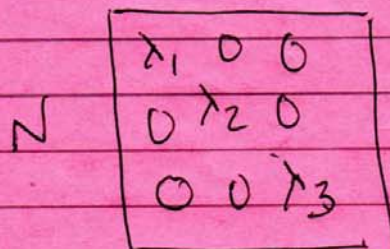
L = diagonal matrix with the eigenvalues λ along the diagonal.



→ Cov. matrix (C)
 (Diagonal elements = variances
 off-diagonal elements = covariances)



→ Eigen vectors (E)
 Each of length (N)



→ Eigenvalues in diagonal matrix L .

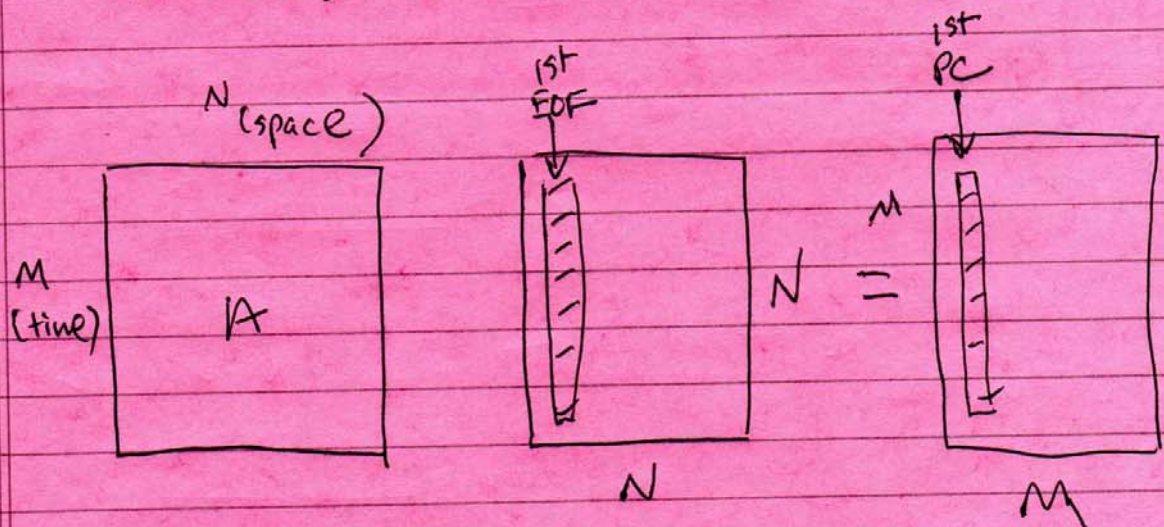
Eigenanalysis acts to transform the covariance matrix into a coordinate space where the "new" matrix is reorganized along the diagonal.

→ Eigen analysis diagonalizes the covariance matrix.

Time series of EOFs - Principal components (PC)

Time series of EOFs, or principal components, found by projecting the data onto the eigen vectors.

$A (M \times N) \cdot e \Rightarrow$ PC time series



The projection of $A \cdot E$ yields a coefficient matrix of the expansion of the data in terms of the eigenvectors. The exp. coef. time series are referred to as the PC time series.